


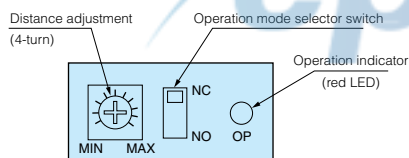


- Unique circuit achieving high accuracy (1 mm = 10 mV)
- Improved resistance to noise by the use of an ultrasonic frequency of 200 kHz
- Resistance to dust and dirt, wide range of detectable objects including transparent objects, liquid, particles, etc.
- Comparator output available

### Type

Type	Detection distance	Model	Operation mode	Output mode
Reflective type	 0.08-1mm	US-1AH	Wave-ON/ Wave-OFF selectable (with switch)	• Analog output
		US-1AHPN		• Comparator output

### Panel layout



- The distance adjustment is a 4-turn volume. Turning clockwise increases the detecting distance up to about 1 m.
- Set the operation mode selector switch according to the application.

NC: Wave-OFF (normally "closed")

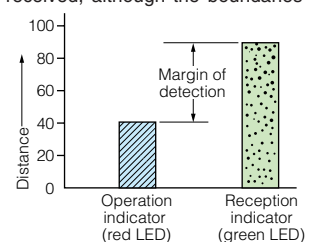
NO: Wave-ON (normally "open")

For using the analog output only, the operation above is unnecessary. Use the sensor with the factory setting enabled.

### Indicators

The reception indicator (green LED) and operation indicator (red LED) on the panel respectively show different received signal levels as described in the figure.

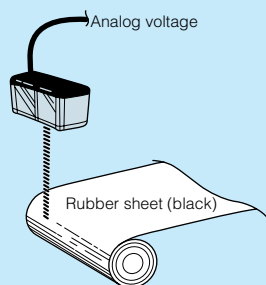
The range of illumination for the operation indicator depends on the distance adjustment setting. The reception indicator is illuminated within the range of distance in which ultrasonic waves are received, although the boundaries may vary depending on the detection object. This indicates a margin of detection.



For detection of object with low ultrasonic reflectance such as rubber, the maximum detecting distance may be reduced.

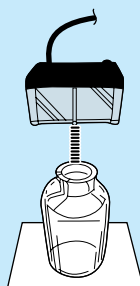
### Sample Applications

- Winding thickness control/measurement

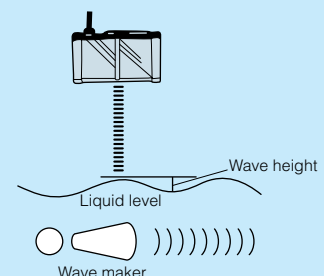


Ultrasonic wave sensor capable of detecting intense black rubber. Analog voltage output available for analog control.

- Detection of transparent objects/bottles



- Analog control of level of liquid/fine particles



Wave height controlled in pool equipped with wave generator.

## Ultrasonic Sensors

## US-1AH (NPN output)

The diagram shows a 4-bit DAC circuit. It features an 'Internal circuit' block containing two comparators (741 op-amp). The circuit is powered by a 5V supply and ground. The output is a 4-bit digital signal (Brown, Black, White, Blue) and an analog output (White). The circuit includes an indicator, a load, and a 600Ω resistor. The output is a 4-bit digital signal (Brown, Black, White, Blue) and an analog output (White). The circuit includes an indicator, a load, and a 600Ω resistor.

Lead colors

Indicator

Internal circuit

Comparator output

Black (White)

White (Green)  
(Analog output)

Blue (Black)

Load  
100 mA max.  
600Ω Min.

Colors in parentheses show previous color-coding

Technical drawing of the SGT-100 ultrasonic sensor, showing three views: top, front, and side.

**Top View Labels:**

- Reception
- Ultrasonic oscillator
- Operation indicator
- SUPER SONIC SENSOR
- STB
- OPL

**Dimensions (mm):**

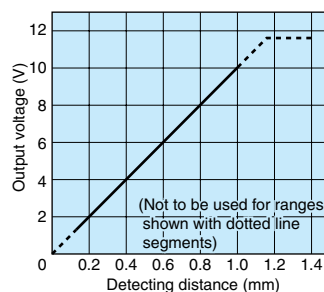
- Top view: 78 (width), 40 (height), 20 (height of mounting flange).
- Front view: 65 (width), 15 (height of top flange), 30 (height of main body), 60 (total height), 9 (height of mounting flange).
- Side view: 13 (width of mounting flange).

**Other Features:**

- Max 0.8 (maximum depth of the sensor head)
- 8-M4 hole of 6 mm in depth (mounting hole)
- Cord 2m (cable length)
- $\phi 6.5$  (cable diameter)

Environmen	Ambient temperature	-10 - +55 °C (non-freezing)
	Ambient humidity	35-85%RH (non-condensing)
	Ambient wind speed	1m/s max
	Protective structure	IP51
	Vibration	10-55 Hz / 1.5 mm amplitude / 2 hours each in 3 directions
	Shock	500 m/s <sup>2</sup> / 2 times each in 3 directions (ultrasonic element excluded)
	Dielectric withstanding	500VAC for 1 minute
	Insulation resistance	500 VDC, 20 MΩ or higher

- Applicable comparator



# Ultrasonic Sensors

## ■ For Correct Use

### Notes on use of ultrasonic sensors

#### ● Installation location and external disturbance

- Although a circuit is employed that uses ultrasonic waves with high oscillation frequency for distinction from external sounds, do not install the sensor in a place subject to frequent sound of glass cutting, sound generated from air nozzles, high-frequency clanks, etc.
- Ultrasonic sensors use air as the transmission medium and places subject to localized temperature change or significant change in convection (air from air conditioner or heat generator) must be avoided.
- While the sensor is waterproofed, note that water on the ultrasonic element (white part on the front of the sensor) may reduce the sensitivity. Also absorption of water may cause deterioration.

#### ● Interference

- Adjacent installation or installation of more than one sensor in a small space may cause interference.
- Prevent faulty operation due to irregular reflection caused by spread of ultrasonic waves especially by side lobe.

### Installation adjustment and objects

#### ● Through-beam type

- Through-beam type offers high sensitivity and reflection on walls or floor may make it difficult to block the signals sufficiently. Apply noise absorbing materials or reduce the sensitivity with the adjustment.

#### ● Reflective type

- Certain limitations apply to objects detectable with reflective type. With objects that may function as noise absorbing materials, soft cloths, sponges, etc., operating distance may be significantly reduced or the sensor may not be activated.  
Transparent or black objects offer the same detecting distances as objects of other colors.  
With objects with polished surfaces like mirrors, the reflected sound waves may not return to the sensor depending on the angle of the passing object.

- Air nozzles may cause variation of the detecting distance. Provide sufficient measures for noise in a place with many nozzles.

#### ● Reflective type analog output

- Certain limitations apply to detectable objects.  
With objects that may function as noise absorbing materials, soft cloths, sponges, etc., operating distance may be significantly reduced or the sensor may not be activated. Use hard objects such as iron plate to check the operation at the same distance.  
Transparent or black objects offer the same detecting distances as objects of other colors. Objects with polished surfaces like mirrors, the reflected sound waves may not return to the sensor depending on the angle of the passing object.
- Detection at the center of ultrasonic wave axis offers normal distance output. For detection of passing objects, set the sensor so that the detection occurs as close to the central axis as possible. The central axes of the sensor and the ultrasonic wave may be apart by a few degrees.
- Dead zone**  
Ultrasonic sensors measure the distance from the object by measuring the time before the reflected ultrasonic waves are received. Reverberation is present in the vicinity of the ultrasonic element and the reception operation is stopped for a certain period for avoiding its effect. In a very short range, reflection and reception of waves may occur more than once between the object and sensor, which generates higher output than for the actual detecting distance and prevents the generation of normal output in proportion to the detecting distance. To avoid such situations, do not use the sensor in the short distance, which is specified as a dead zone.
- Running time**  
After power-up, it takes about 30 minutes before the analog output stabilizes. For measurement or operation requiring accuracy, supply power well in advance.
- Sensor mounting**  
Ultrasonic waves spread over a large angle and the angle of the object may significantly affect detection. Be sure to mount the sensor in such a way that it faces the surface to be detected at right angles except for objects that reflect waves diffusely such as fine particles.

## ■ Major Applications of Ultrasonic Sensors

Classification	Application
Detection of passage or presence, counting	<ul style="list-style-type: none"> <li>●Detection of passage of bottles or corrugated cardboard</li> <li>●Detection of sheets</li> <li>●Detection of papers</li> <li>●Presence of wood materials or processed goods</li> <li>●Presence of glass plates</li> </ul>
Level detection	<ul style="list-style-type: none"> <li>●Detection of level of fine particles in hopper</li> <li>●Detection of level of grain, feedstuff, etc.</li> <li>●Detection of height of piles</li> <li>●Detection of chemicals, etc. in hopper</li> <li>●Detection of water level</li> </ul>
Sorting	<ul style="list-style-type: none"> <li>●Sorting by height of packages</li> <li>●Detection of height of vehicles</li> </ul>
Constant rate feeding/positioning	<ul style="list-style-type: none"> <li>●Detection of stopping position of unmanned carriages</li> <li>●Detection of sag or winding length of rolled materials</li> </ul>
Safety/alert	<ul style="list-style-type: none"> <li>●Prevention of collision of cranes</li> <li>●Detection of height of vehicles</li> <li>●Detection of height of piles of goods</li> <li>●Detection of ingress</li> </ul>